

## T-SERIES ACTUATOR®

This series of powerful robot actuators allows engineers, researchers, and industrial integrators to quickly and easily create world-class custom robots of any configuration.

T-Series Actuators® are packed with sensors that enable controllable position, velocity, and sensitive torque control as well as three axis inertial measurement.

Each series elastic actuator integrates a brushless motor, gear train, spring, encoders, and control electronics into a compact package that runs on anything from 24V-48V DC and communicates using standard 10/100Mbps Ethernet.





The T-Series Actuator® is designed to function as a full-featured robotic component as opposed to a simple servo motor. The output rotates continuously, requires no calibration or homing on boot-up, and contains a thru-bore for easy daisy-chaining and wiring. This feature enables these actuators to be used in everything from wheeled robots to multidegree of freedom collaborative robotic arms.

 The T25 actuators offer the highest mechanical power, improved current sensing, and longer durability.

HEBI Robotics provides cross-platform software tools that make configuring and controlling the T-Series a breeze, with features such as live plotting, APIs for MATLAB, ROS, C/C++, and Python.



## T-SERIES ACTUATOR® — TECHNICAL SPECIFICATIONS

Configuration	T5-1	T5-4	T5-9	T8-3+	T8-9+	T8-16+	T25-8	T25-20	T25-40
Peak Torque	2.5 N-m	7 N-m	13 N-m	8 N-m	23 N-m	44 N-m	16 N-m	40 N-m	80 N-m
Cont. Torque	1.3 N-m	4 N-m	8 N-m	4 N-m	10 N-m	20 N-m	8 N-m	20 N-m	40 N-m
Max Speed	90 RPM	32 RPM	14 RPM	110 RPM		20 RPM	118 RPM	47 RPM	23 RPM
Mass	450g			575g			1.5kg		
Dimensions	126mm x 74mm x 34mm 15mm hollow bore			126mm x 74mm x 48mm 15mm hollow bore			170mm x 105mm x 67mm 20mm hollow bore		
Power	24-48V DC			24-48V DC			36-48V DC		
	Cont. Current: 0.5A @ 36V			Cont. Current: 1.0A @ 36V			Cont. Current: 1.5A @ 36V		
	Peak Current: 1.6A @ 36V			Peak Current: 2.5A @ 36V			Peak Current: 5A @ 36V		
Environment	-10°C to 50°C Ambient / Designed for IP65								
Communication	2x 100 Mbps Plastic Optical Fiber (OptoLock®)								
<b>Angular Resolution</b>	0.005°								
<b>Torque Resolution</b>	0.01 N-m								
Backlash	+/- 0.25°								
Sensing	Angular Position (multi-turn absolute, +/- 4 turns)								
	Angular Velocity								
	Output Torque								
	3-axis Accelerometer / Gyro								
	Motor and Electronics Temperature								
	Voltage								
	Current								
	Internal Pressure								
API Support	MATLAB (Windows / Linux / OS X)								
	ROS (Linux)								
	Python (Windows / Linux / OS X)								
	C/C++ (Windows / Linux / OS X)								
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Updated on July 25, 2024. Specifications subject to change without notice.

